

Newton's iteration for quadratic equations

David L. Duncan

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1 Overview

In these notes I review Newton's iteration associated to an equation $\mathcal{F}(x) = 0$. I will address convergence of the iteration, and the induced map that is defined when the initial condition is allowed to vary. I am primarily interested in how the various constants depend on the first and second derivatives of \mathcal{F} . The primary application is to the case where \mathcal{F} is a linear expression in the curvature of a connection, so I largely focus on the case where the defining equation \mathcal{F} is quadratic.

In many ways my argument below mimics that of [1, Section 5]. Indeed, my original aim was to extend their result (which applies to mapping tori) to the quilted case described in [2] (which applies, more generally, to manifolds with positive first Betti number). Unfortunately, the scaling does not behave favorably in the more general quilted case. I hope to eventually include a more detailed description of this failure in these notes.

2 Banach space set-up

Suppose \mathcal{X}, \mathcal{Y} are Banach spaces and $\mathcal{F} : \mathcal{X} \rightarrow \mathcal{Y}$ is a smooth function. Using Taylor's theorem, we can write

$$\mathcal{F}(x + v) = \mathcal{F}(x) + D_x \mathcal{F}(v) + R_x(v)$$

for some quadratically bounded $R_x(v)$. For our applications we will be interested in the case where \mathcal{F} is quadratic, in which case $R_x(v) = D_x^2 \mathcal{F}(v, v)$ is a quadratic form (the Hessian).

Lemma 2.1. For each $x \in \mathcal{X}$ there are constants $d_2 > 0$ and $\epsilon_0 > 0$, possibly depending on x , such that

$$\|R_x(v) - R_x(w)\|_{\mathcal{Y}} \leq d_2 (\|v\|_{\mathcal{X}} + \|w\|_{\mathcal{X}}) \|v - w\|_{\mathcal{X}}$$

for all $v, w \in T_x \mathcal{X} = \mathcal{X}$ with $\|v\|_{\mathcal{X}}, \|w\|_{\mathcal{X}} < \epsilon_0$. If \mathcal{F} is quadratic, then the result holds with $\epsilon_0 = \infty$.

Proof. We prove this in the case where \mathcal{F} is quadratic; for the more general case, see any book on the implicit function theorem. In the quadratic case, we have

$$R_x(v) - R_x(w) = D_x^2 \mathcal{F}(v, v) - D_x^2 \mathcal{F}(w, w) = D_x^2 \mathcal{F}(v, v - w) + D_x^2 \mathcal{F}(w, v - w).$$

Then the result follows by taking d_2 to be the operator norm of $D_x^2 \mathcal{F}$. \square

In particular, we have the following bound:

$$\|R_x(v)\|_{\mathcal{Y}} \leq d_2 \|v\|_{\mathcal{X}}^2, \quad (1)$$

for all v satisfying the conditions of the Lemma.

We also need an estimate on the first derivative $D_x \mathcal{F}$. We begin by assuming that $D_x \mathcal{F}$ is surjective, and let M_x be a right inverse:

$$(D_x \mathcal{F})M_x = \text{Id}_{\mathcal{Y}}.$$

We assume that M_x satisfies

$$\|M_x w\|_{\mathcal{X}} \leq d_1 \|w\|_{\mathcal{Y}}. \quad (2)$$

In general $d_1 = d_1(x)$ is independent of $w \in T_{\mathcal{F}(x)} \mathcal{Y} = \mathcal{Y}$, but may depend on $x \in \mathcal{X}$.

Theorem 2.2. (*Newton's iteration*) Suppose $D_x \mathcal{F}$ is surjective for all $x \in X$, and let d_1, d_2 and ϵ_0 be as above. Assume these constants can be chosen to be independent of $x \in \mathcal{X}$. Let $\delta > 0$ be any constant with $\delta d_1 \leq \epsilon_0$ and $\delta^2 d_1 < 1$. Suppose there is some $x_0 \in \mathcal{X}$ with $\|\mathcal{F}(x_0)\|_{\mathcal{Y}} \leq \delta$. Then there is some $x_\infty \in \mathcal{X}$ with $\mathcal{F}(x_\infty) = 0$, and

$$\|x_\infty - x_0\|_{\mathcal{X}} \leq \frac{d_1 d_2}{1 - \delta^2 d_1}.$$

Moreover, there is at most one zero x_∞ of \mathcal{F} satisfying

$$\|x_\infty - x_0\| < \min \left\{ \frac{1}{2d_1 d_2}, \epsilon_0 \right\}.$$

This theorem implies the existence of a map

$$\mathcal{T} : \mathcal{F}^{-1}(B_\delta(0)) \longrightarrow \mathcal{X}$$

with the property that $\mathcal{F}(\mathcal{T}(x)) = 0$ for all $x \in \mathcal{F}^{-1}(B_\delta(0))$, and \mathcal{T} is locally injective.

Remark 2.3. (a) More generally, suppose the image $\text{im } D_x \mathcal{F} \subset \mathcal{Y}$ is closed as a Banach subspace that is independent of x . Then by replacing \mathcal{Y} with this image we obtain a situation where the linearization is surjective. However, if this image depends on x then Newton's iteration breaks down, in general.

(b) This theorem has various straight-forward extensions to the case where any of d_1, d_2 or ϵ_0 depends on $x \in \mathcal{X}$. For example, in our proof we use δ to measure the smallness of $\|\mathcal{F}(x_0)\|_{\mathcal{Y}}$ and this translates to a measure of the closeness of x_0 and x_∞ . A more sophisticated treatment would measure these using separate parameters. The precise way in which one would do this depends on the specific application (e.g., how good of an initial guess x_0 is relative to the value of the constants d_1, d_2), so here we only address the simplest case where the constants do not depend on x .

Proof of Theorem 2.2. Given x_0 , define a sequence $\{x_n\}$ recursively by

$$x_{n+1} := x_n - M_{x_n} \mathcal{F}(x_n).$$

We will prove the following by induction on n :

- (A) $\|x_{n+1} - x_n\|_{\mathcal{X}} \leq d_1 \|\mathcal{F}(x_n)\|_{\mathcal{Y}}$
- (B) $\|\mathcal{F}(x_{n+1})\|_{\mathcal{Y}} \leq d_1 d_2 \|\mathcal{F}(x_n)\|_{\mathcal{Y}}^2$
- (C) $\|x_{n+1} - x_n\|_{\mathcal{X}} \leq d_1 d_2 (\delta^2 d_1)^n$
- (D) $\|\mathcal{F}(x_n)\|_{\mathcal{Y}} \leq d_2 (\delta^2 d_1)^n$.

The proof of (A) is immediate from the definition of the x_n . For (B), we use the Taylor expansion of \mathcal{F} :

$$\begin{aligned} \|\mathcal{F}(x_{n+1})\|_{\mathcal{Y}} &= \|\mathcal{F}(x_n - M_{x_n} \mathcal{F}(x_n))\|_{\mathcal{Y}} \\ &= \|\mathcal{F}(x_n) - D_{x_n} \mathcal{F}(M_{x_n} \mathcal{F}(x_n)) + R_{x_n}(-M_{x_n} \mathcal{F}(x_n))\|_{\mathcal{Y}} \\ &= \|R_{x_n}(-M_{x_n} \mathcal{F}(x_n))\|_{\mathcal{Y}} \\ &\leq d_1 d_2 \|\mathcal{F}(x_n)\|_{\mathcal{Y}}^2. \end{aligned}$$

In the inequality we used (1), and the assumption $\delta_0 d_1 \leq \epsilon_0$. Now we use (A) and (B) to prove (C) and (D):

$$\begin{aligned} \|x_{n+1} - x_n\|_{\mathcal{X}} &\leq d_1 \|\mathcal{F}(x_n)\|_{\mathcal{Y}} \\ &\leq d_1^2 d_2 \|\mathcal{F}(x_{n-1})\|_{\mathcal{Y}}^2 \\ &\quad \vdots \\ &\leq d_1^{n+1} d_2 \|\mathcal{F}(x_0)\|_{\mathcal{Y}}^{2n} \\ &\leq d_1 d_2 (\delta^2 d_1)^n. \end{aligned}$$

This finishes the induction.

It follows from (C) that $\{x_n\}$ is Cauchy:

$$\begin{aligned} \|x_{n+k} - x_n\|_{\mathcal{X}} &\leq \sum_{j=0}^{k-1} \|x_{n+j+1} - x_{n+j}\|_{\mathcal{X}} \\ &\leq d_1 d_2 (\delta^2 d_1)^n \sum_{j=0}^{k-1} (\delta^2 d_1)^j \\ &\leq d_1 d_2 (\delta^2 d_1)^n \frac{1}{1 - \delta^2 d_1}, \end{aligned}$$

which goes to zero in n , since $\delta_0^2 d_1 < 1$. We set $x_\infty = \lim_{n \rightarrow \infty} x_n$. Taking $n = 0$, and taking k to ∞ , the above computation also shows

$$\|x_\infty - x_0\|_{\mathcal{X}} \leq \frac{d_1 d_2}{1 - \delta^2 d_1}.$$

Similarly, it follows from (D) that $\mathcal{F}(x_\infty) = 0$.

Finally, suppose $x_\infty, x'_\infty \in \mathcal{X}$ are two distinct zeros of \mathcal{F} satisfying $\|x_\infty - x_0\| < 1/2d_1d_2$ and $\|x'_\infty - x_0\| < 1/2d_1d_2$. Then we have

$$D_{x_0} \mathcal{F}(x'_\infty - x_\infty) = R_{x_0}(x'_\infty - x_0) - R_{x_0}(x_\infty - x_0),$$

so by Lemma 2.1 we get

$$\begin{aligned} \|x'_\infty - x_\infty\|_{\mathcal{X}} &\leq d_1 \|R_{x_0}(x'_\infty - x_0) - R_{x_0}(x_\infty - x_0)\|_{\mathcal{Y}} \\ &\leq d_1 d_2 (\|x'_\infty - x_0\|_{\mathcal{X}} + \|x_\infty - x_0\|_{\mathcal{X}}) \|x'_\infty - x_\infty\|_{\mathcal{X}} \\ &< \|x'_\infty - x_\infty\|_{\mathcal{X}} \end{aligned}$$

which is impossible. So we must have $x'_\infty = x_\infty$. \square

3 Applications to the curvature

Let (Z, g) be a smooth, compact, oriented Riemannian 4-manifold. Fix a principal G -bundle $P \rightarrow Z$ and a smooth reference connection on P . Let \mathcal{X} be the $W^{1,2}$ -completion of the compactly supported elements of $\Omega^1 := \Omega^1(Z, P(\mathfrak{g}))$, and let \mathcal{Y} be the L^2 -completion of the compactly supported elements of $\Omega^+ := \Omega^+(Z, P(\mathfrak{g}))$, where the superscript $+$ denotes self-dual 2-forms. Define $\mathcal{F} : \mathcal{X} \rightarrow \mathcal{Y}$ by

$$\mathcal{F}(x) := F_{A+x}^+ = F_A^+ + d_A^+ x + \frac{1}{2} [x \wedge x]^+.$$

Since \mathcal{F} is quadratic we can take $\epsilon_0 = \infty$ in the statement of Lemma 2.1. Moreover, the quadratic part is $\frac{1}{2} [x \wedge x]^+$, and so is bounded in norm by $d_2 \|x\|_{W^{1,2}}^2$, where d_2 is the Sobolev multiplication constant $W^{1,2} \otimes W^{1,2} \rightarrow L^2$. In particular, d_2 is independent of A and x .

To address d_1 , we need to assume A has been chosen so that d_A^+ maps surjectively onto $\Omega^+(Z, P(\mathfrak{g}))$ (this can be achieved if A is near the space of instantons, and the function \mathcal{F} is suitably perturbed, but we will ignore these issues). It follows that d_{A+x}^+ is also surjective, provided x is sufficiently small. Moreover, general elliptic theory implies that the formal (L^2) adjoint $d_{A+x}^* : \Omega^+ \rightarrow \Omega^1$ is injective, and that the operator $d_{A+x}^+ d_{A+x}^* : \Omega^+ \rightarrow \Omega^+$ extends to a Banach space isomorphism from the $W^{2,2}$ -completion of the domain to the L^2 -completion of the codomain; let $(d_{A+x}^+ d_{A+x}^*)^{-1}$ denote the inverse of this operator. Define

$$M_x := d_{A+x}^* (d_{A+x}^+ d_{A+x}^*)^{-1} : \Omega^+ \longrightarrow \Omega^1,$$

which extends to a bounded map $\mathcal{Y} \rightarrow \mathcal{X}$. This is a right inverse of $D_x \mathcal{F}$ and, since M_x is bounded, there is constant d_1 with

$$\|M_x w\|_{\mathcal{X}} \leq d_1 \|w\|_{\mathcal{Y}}$$

for all $w \in \mathcal{Y}$. This depends on x , but not on w .

We want to import the theory from the previous section. The only issue is that d_1 does depend on the basepoint x , and so does not quite fit into the formalism of Theorem 2.2; however, see Remark 2.3 (b).

The long-term goal of this section is to understand the dependence of the constants d_1, d_2 on the metric g , and then use the appropriate extension of Theorem 2.2 to translate this into a condition on the smallness of $\|\mathcal{F}(V)\|_{L^2}$ (i.e., via the value of δ). The particular situation we have in mind is when $g = g_\epsilon$, where g_ϵ is a metric as in [2]. Here $\epsilon > 0$ is a parameter that measures the smallness in certain directions, and the goal of [2] is to investigate the limit as ϵ approaches zero. Here we would be interested in seeing how δ depends on ϵ ...

References

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- [2] D. Duncan. Higher rank instanton Floer theory and the quilted Atiyah-Floer conjecture. arXiv:1311.5609.